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Fractional Dynamics and Control provides a comprehensive overview of recent advances in the areas of nonlinear dynamics, vibration and control with analytical, numerical, and experimental results. This book provides an overview of recent discoveries in fractional control, delves into fractional variational principles and differential equations, and applies advanced techniques in fractional calculus to solving complicated mathematical and physical problems. Finally, this book also discusses the role that fractional order modeling can play in complex systems for engineering and science. This self-contained introduction to practical robot kinematics and dynamics includes a comprehensive treatment of robot control. It provides background material on terminology and linear transformations, followed by coverage of kinematics and inverse kinematics, dynamics, manipulator control, robust control, force control, use of feedback in nonlinear systems, and adaptive control. Each topic is supported by examples of specific applications. Derivations and proofs are included in many cases. The book includes many worked examples, examples illustrating all aspects of the theory, and problems. This multi-authored volume presents selected papers from the Eighth Workshop on Dynamics and Control. Many of the papers represent significant advances in this area of research, and cover the development of control methods, including the control of dynamical systems subject to mixed constraints on both the control and state variables, and the development of a control design method for flexible manipulators with mismatched uncertainties. Advances in dynamic systems are presented, particularly in game-theoretic approaches and also the applications of dynamic systems methodology to social and environmental problems, for example, the concept of virtual biospheres in modeling climate change in terms of dynamical systems. Spacecraft Dynamics and Control: The Embedded Model Control Approach provides a uniform and systematic way of approaching space engineering control problems from the standpoint of model-based control, using state-space equations as the key paradigm for simulation, design and implementation. The book introduces the Embedded Model Control methodology for the design and implementation of attitude and orbit control systems. The logic architecture is organized around the embedded model of the spacecraft and its surrounding environment. The model is compelled to include disturbance dynamics as a repository of the uncertainty that the control law must reject to meet attitude and orbit requirements within the uncertainty class. The source of the real-time uncertainty estimation/prediction is the model error signal, as it encodes the residual discrepancies between spacecraft measurements and model output. The embedded model and the uncertainty estimation feedback (noise estimator in the book) constitute the state predictor feeding the control law. Asymptotic pole placement (exploiting the asymptotes of closed-loop transfer functions) is the way to design and tune feedback loops around the embedded model (state predictor, control law, reference generator). The design versus the uncertainty class is driven by analytic stability and performance inequalities. The method is applied to several attitude and orbit control problems. The book begins with an extensive introduction to attitude geometry and algebra and ends with the core themes: state-space dynamics and Embedded Model Control. Fundamentals of orbit, attitude and environment dynamics are treated giving emphasis to state-space formulation, disturbance dynamics, state feedback and prediction, closed-loop stability. Sensors and actuators are treated giving emphasis to their dynamics and modelling of measurement errors. Numerical tables are included and their data employed for numerical simulations. Orbit and attitude control problems of the European GOCE mission are the inspiration of numerical exercises and simulations. The suite of the attitude control modes of a GOCE-like mission is designed and simulated around the so-called mission state predictor. Solved and unsolved exercises are included within the text - and not separated at the end of chapters - for better understanding, training and application. Simulated results and their graphical plots are developed through MATLAB/Simulink code. Whereas power systems have traditionally been designed with a focus on protecting them from routine component failures and atypical user demand, we now also confront the fact that deliberate attack intended to cause maximum disruption is a real possibility. In response to this changing environment, new concepts and tools have emerged that address many of the issues facing power system operation today. This book is aimed at introducing these ideas to practicing power systems engineers, control systems engineers interested in power systems, and graduate students in these areas. The ideas are examined with an emphasis on how they can be applied to improve our understanding of power system behavior and help design better control systems. The book is supplemented by a Mathematica package enabling readers to work out nontrivial examples and problems. Also included is a set of Mathematica tutorial notebooks providing detailed solutions of the worked examples in the text. In addition to Mathematica, simulations are carried out using Simulink with Stateflow. One of the first books to provide in-depth and systematic application of finite element methods to the field of stochastic structural dynamics The parallel developments of the Finite Element Methods in the 1950's and the engineering applications of stochastic processes in the 1940's provided a combined numerical analysis tool for the studies of dynamics of structures and structural systems under random loadings. In the open literature, there are books on statistical dynamics of structures and books on structural dynamics with chapters dealing with random response analysis. However, a systematic treatment of stochastic structural dynamics applying the finite element methods seems to be lacking. Aimed at advanced and specialist levels, the author presents and illustrates analytical and direct integration methods for analyzing the statistics of the response of structures to stochastic loads. The analysis methods are based on structural models represented via the Finite Element Method. In addition to linear problems the text also addresses nonlinear problems and non-stationary random excitation with systems having large spatially stochastic property variations. Aircraft Flight Dynamics and Control addresses airplane flight dynamics and control in a largely classical manner, but with references to modern treatment throughout. Classical feedback control methods are illustrated with relevant examples, and current trends in control are presented by introductions to dynamic inversion and control allocation. This book covers the physical and mathematical fundamentals of aircraft flight dynamics as well as more advanced theory enabling a better insight

into nonlinear dynamics. This leads to a useful introduction to automatic flight control and stability augmentation systems with discussion of the theory behind their design, and the limitations of the systems. The author provides a rigorous development of theory and derivations and illustrates the equations of motion in both scalar and matrix notation. Key features: Classical development and modern treatment of flight dynamics and control Detailed and rigorous exposition and examples, with illustrations Presentation of important trends in modern flight control systems Accessible introduction to control allocation based on the author's seminal work in the field Development of sensitivity analysis to determine the influential states in an airplane's response modes End of chapter problems with solutions available on an accompanying website Written by an author with experience as an engineering test pilot as well as a university professor, Aircraft Flight Dynamics and Control provides the reader with a systematic development of the insights and tools necessary for further work in related fields of flight dynamics and control. It is an ideal course textbook and is also a valuable reference for many of the necessary basic formulations of the math and science underlying flight dynamics and control. An integrated presentation of dynamics, vibrations, and control theory, emphasizing the fundamentals of dynamics. The text's flexible structure makes it useful for integrated courses covering all three areas, individual courses in dynamics, and as a quick refresher for professionals. Includes examples, problems and applications. Basic models and concepts of machine dynamics and motion control are presented in the order of the principal steps of machine design. The machine is treated as a coupled dynamical system, including drive, mechanisms and controller, to reveal its behavior at different regimes through the interaction of its units under dynamic and processing loads. The main dynamic effects in machines are explained. The influence of component compliances on accuracy, stability and efficiency of the machines is analyzed. Methods for decreasing internal and external vibration activity of machines are described. The dynamic features of digital control are considered. Special attention is given to machines with intense dynamic behavior: resonant and hand-held percussion ones. Targeted to engineers as well as to lecturers and advanced students. A textbook that incorporates the latest methods used for the analysis of spacecraft orbital, attitude, and structural dynamics and control. Spacecraft dynamics is treated as a dynamic system with emphasis on practical applications, typical examples of which are the analysis and redesign of the pointing control system of the Hubble Space Telescope and the analysis of an active vibrations control for the COFS (Control of Flexible Structures) Mast Flight System. In addition to the three subjects mentioned above, dynamic systems modeling, analysis, and control are also discussed. Annotation copyrighted by Book News, Inc., Portland, OR This new text/reference is an excellent resource for the foundations and applications of control theory and nonlinear dynamics. All graduates, practitioners, and professionals in control theory, dynamical systems, perturbation theory, engineering, physics and nonlinear dynamics will find the book a rich source of ideas, methods and applications. With its careful use of examples and detailed development, it is suitable for use as a self-study/reference guide for all scientists and engineers. This book is a result of many years of author's research and teaching on random vibration and control. It was used as lecture notes for a graduate course. It provides a systematic review of theory of probability, stochastic processes, and stochastic calculus. The feedback control is also reviewed in the book. Random vibration analyses of SDOF, MDOF and continuous structural systems are presented in a pedagogical order. The application of the random vibration theory to reliability and fatigue analysis is also discussed. Recent research results on fatigue analysis of non-Gaussian stress processes are also presented. Classical feedback control, active damping, covariance control, optimal control, sliding control of stochastic systems, feedback control of stochastic time-delayed systems, and probability density tracking control are studied. Many control results are new in the literature and included in this book for the first time. The book serves as a reference to the engineers who design and maintain structures subject to harsh random excitations including earthquakes, sea waves, wind gusts, and aerodynamic forces, and would like to reduce the damages of structural systems due to random excitations. · Comprehensive review of probability theory, and stochastic processes · Random vibrations · Structural reliability and fatigue, Non-Gaussian fatigue · Monte Carlo methods · Stochastic calculus and engineering applications · Stochastic feedback controls and optimal controls · Stochastic sliding mode controls · Feedback control of stochastic time-delayed systems · Probability density tracking control Satellites are used increasingly in telecommunications, scientific research, surveillance, and meteorology, and these satellites rely heavily on the effectiveness of complex onboard control systems. This book explains the basic theory of spacecraft dynamics and control and the practical aspects of controlling a satellite. The emphasis throughout is on analyzing and solving real-world engineering problems. For example, the author discusses orbital and rotational dynamics of spacecraft under a variety of environmental conditions, along with the realistic constraints imposed by available hardware. This brief presents several aspects of flight dynamics, which are usually omitted or briefly mentioned in textbooks, in a concise, self-contained, and rigorous manner. The kinematic and dynamic equations of an aircraft are derived starting from the notion of the derivative of a vector and then thoroughly analysed, interpreting their deep meaning from a mathematical standpoint and without relying on physical intuition. Moreover, some classic and advanced control design techniques are presented and illustrated with meaningful examples. Distinguishing features that characterize this brief include a definition of angular velocity, which leaves no room for ambiguities, an improvement on traditional definitions based on infinitesimal variations. Quaternion algebra, Euler parameters, and their role in capturing the dynamics of an aircraft are discussed in great detail. After having analyzed the longitudinal- and lateral-directional modes of an aircraft, the linear-quadratic regulator, the linear-quadratic Gaussian regulator, a state-feedback H-infinity optimal control scheme, and model reference adaptive control law are applied to aircraft control problems. To complete the brief, an appendix provides a compendium of the mathematical tools needed to comprehend the material presented in this brief and presents several advanced topics, such as the notion of semistability, the Smith-McMillan form of a transfer function, and the differentiation of complex functions: advanced control-theoretic ideas helpful in the analysis presented in the body of the brief. A Mathematical Perspective on Flight Dynamics and Control will give researchers and graduate students in aerospace control an alternative, mathematically rigorous means of approaching their subject. This applied and comprehensive book combines topical coverage of both System Dynamics and Automatic Controls in one text, resulting in a pedagogically sound presentation of both subjects that can be used in this standard two-course sequence. It is thorough and complete, with, according to one reviewer, a "tremendous number of interesting practice problems covering a broad range of areas, giving the instructor significant choice and flexibility" in teaching the material. The book also has a wealth of worked-out, real-world examples, with every step clearly shown and explained. Cumulative examples that build through succeeding chapters demonstrate the stages of system modeling, from initial steps - which include the important but often omitted physical modeling process - through mathematical analysis to design realization. The result is a new and unified presentation of system dynamics and control, founded on a wide range of systems (mechanical, electrical, electromechanical - including MEMS, fluid, thermal, and chemical), with a common state-space approach. Mechanical engineering, and engineering discipline born of the needs of the industrial revolution, is once again asked to do its substantial share in the call for industrial renewal. The general call is urgent as we face p- found issues of productivity and competitiveness that require engineering solutions, among others. The Mechanical Engineering Series is a series f- turing graduate texts and research monographs intended to address the need for information in contemporary areas of mechanical engineering. The series is conceived as a comprehensive one that covers a broad range of concentrations important to mechanical engineering graduate - ucation and research. We are fortunate to have a distinguished roster of series editors, each an expert in one of the areas of concentration. The names of the series editors are listed on page vi of this volume. The areas of concentration are applied mechanics, biomechanics, computational - chanics, dynamic systems and control, energetics, mechanics of materials, processing, thermal science, and tribology. Preface After 15 years since the publication of Vibration of Structures and Machines and three subsequent editions a deep reorganization and updating of the material was felt necessary. This new book on the subject of Vibration dynamics and control is organized in a larger number of shorter chapters, hoping that this can be helpful to the reader. New material has been added and many points have been updated. A larger number of examples and of exercises have been included. Science is for those who learn; poetry for those who know. —Joseph Roux This book is a continuation of my previous book, Dynamics and Control of Structures [44]. The expanded book includes three additional chapters and an additional appendix: Chapter 3, "Special Models"; Chapter 8, "Modal Actuators and Sensors"; and Chapter 9, "System Identification. " Other chapters have been significantly revised and supplemented with new topics, including discrete-time models of structures, limited-time and -frequency grammians and reduction, almo- balanced modal models, simultaneous placement of sensors and actuators, and structural damage detection. The appendices have also been updated and expanded. Appendix A consists of thirteen new Matlab programs. Appendix B is a new addition and includes eleven Matlab programs that solve examples from each chapter. In Appendix C model data are given. Several books on structural dynamics and control have been published. Meirovitch's textbook [108] covers methods of structural dynamics (virtual work, d'Alambert's principle, Hamilton's principle, Lagrange's and Hamilton's equations, and modal analysis of structures) and control (pole placement methods, LQG design, and modal control). Ewins's book [33] presents methods of modal testing of structures. Natke's book [111] on structural identification also contains excellent material on structural dynamics. Fuller, Elliot, and Nelson [40] cover problems of structural active control and structural acoustic control. This book discusses relevant microgrid technologies in the context of integrating renewable energy and also addresses challenging issues. The authors summarize long term academic and research outcomes and contributions. In addition, this book is influenced by the authors' practical experiences on microgrids (MGs), electric network monitoring, and control and power electronic systems. A thorough discussion of the basic principles of the MG modeling and operating issues is provided. The MG structure, types, operating modes, modelling, dynamics, and control levels are covered. Recent advances in DC microgrids, virtual synchronous generators, MG planning and energy management are examined. The physical constraints and engineering aspects of the MGs are covered, and developed robust and intelligent control strategies are discussed using real time simulations and experimental studies. This monograph is intended to provide a snapshot of the status and opportunities for advancement in the technologies of dynamics and control of large flexible spacecraft structures. It is a reflection of the serious dialog and assessments going on all over the world, across a wide variety of scientific and technical disciplines, as we contemplate the next major milestone in mankind's romance with space: the transition from exploration and experimentation to commercial and defense exploitation. This exploitation is already in full swing in the space communications area. Both military and civilian objectives are being pursued with increasingly more sophisticated systems such as large antenna reflectors with active shape control. Both the NATO and Warsaw pact alliances are pursuing permanent space stations in orbit: large structural systems whose development calls for in-situ fabrication and/or assembly and whose operation will demand innovations in controls technology. The last ten years have witnessed a fairly brisk research activity in the dynamics and control of large space structures in order to establish a technology base for the development of advanced spacecraft systems envisioned for the future. They have spanned a wide spectrum of activity from fundamental methods development to systems concept studies and laboratory experimentation and demonstrations. Some flight experiments have also been conducted for various purposes such as the characterization of the space environment, durability of materials and devices in that environment, assembly and repair operations, and the dynamic behavior of flexible structures. It is this last area that has prompted this monogram. Vehicle Dynamics and Control provides a comprehensive coverage of vehicle control systems and the dynamic models used in the development of these control systems. The control system applications covered in the book include cruise control, adaptive cruise control, ABS, automated lane keeping, automated highway systems, yaw stability control, engine control, passive, active and semi-active suspensions, tire-road friction coefficient estimation, rollover prevention, and hybrid electric vehicles. In developing the dynamic model for each application, an effort is made to both keep the model simple enough for control system design but at the same time rich enough to capture the essential features of the dynamics. A special effort has been made to explain the several different tire models commonly used in literature and to interpret them physically. In the second edition of the book, chapters on roll dynamics, rollover prevention and hybrid electric vehicles have been added, and the chapter on electronic stability control has been enhanced. The use of feedback control systems on automobiles is growing rapidly. This book is intended to serve as a useful resource to researchers who work on the development of such control systems, both in the automotive industry and at universities. The book can also serve as a textbook for a graduate level course on Vehicle Dynamics and Control. This book addresses problems in structural dynamics and control encountered in applications such as robotics, aerospace structures, earthquake-damage prevention, and active noise suppression. The rapid developments of new technologies and computational power have made it possible to formulate and solve

engineering problems that seemed unapproachable only a few years ago. This presentation combines concepts from control engineering (such as system norms and controllability) and structural engineering (such as modal properties and models), thereby revealing new structural properties as well as giving new insight into well-known laws. This book will assist engineers in designing control systems and dealing with the complexities of structural dynamics. Converter-Based Dynamics and Control of Modern Power Systems addresses the ongoing changes and challenges in rotating masses of synchronous generators, which are transforming dynamics of the electrical system. These changes make it more important to consider and understand the role of power electronic systems and their characteristics in shaping the subtleties of the grid and this book fills that knowledge gap. Balancing theory, discussion, diagrams, mathematics, and data, this reference provides the information needed to acquire a thorough overview of resilience issues and frequency definition and estimation in modern power systems. This book offers an overview of classical power system dynamics and identifies ways of establishing future challenges and how they can be considered at a global level to overcome potential problems. The book is designed to prepare future engineers for operating a system that will be driven by electronics and less by electromechanical systems. Includes theory on the emerging topic of electrical grids based on power electronics Creates a good bridge between traditional theory and modern theory to support researchers and engineers Links the two fields of power systems and power electronics in electrical engineering This book introduces and develops the mathematical models used to describe crane dynamics, and explores established and emerging control methods employed for industrial cranes. It opens with a general introduction to the design and structure of various crane types including gantry cranes, rotary cranes, and mobile cranes currently being used for material handling processes. Mathematical models describing their dynamics for control purposes are developed via two different modeling approaches: lumped-mass and distributed parameter models. Control strategies applicable to real industrial problems are then discussed, including open-loop control, feedback control, boundary control, and hybrid control strategies. Finally, based on the methods covered in the book, future research directions are proposed for the advancement of crane technologies. This book can be used by graduate students, engineers, and researchers in the material handling industry including those working in warehouses, manufacturing, construction sites, ship building, seaports, container terminals, nuclear power plants, and in offshore engineering. A textbook that incorporates the latest methods used for the analysis of spacecraft orbital, attitude, and structural dynamics and control. Spacecraft dynamics is treated as a dynamic system with emphasis on practical applications, typical examples of which are the analysis and redesign of the pointing control system of the Hubble Space Telescope and the analysis of an active vibrations control for the COFS (Control of Flexible Structures) Mast Flight System. In addition to the three subjects mentioned above, dynamic systems modeling, analysis, and control are also discussed. Annotation copyrighted by Book News, Inc., Portland, OR A comprehensive review of the principles and dynamics of robotic systems Dynamics and Control of Robotic Systems offers a systematic and thorough theoretical background for the study of the dynamics and control of robotic systems. The authors—noted experts in the field—highlight the underlying principles of dynamics and control that can be employed in a variety of contemporary applications. The book contains a detailed presentation of the precepts of robotics and provides methodologies that are relevant to realistic robotic systems. The robotic systems represented include wide range examples from classical industrial manipulators, humanoid robots to robotic surgical assistants, space vehicles, and computer controlled milling machines. The book puts the emphasis on the systematic application of the underlying principles and show how the computational and analytical tools such as MATLAB, Mathematica, and Maple enable students to focus on robotics' principles and theory. Dynamics and Control of Robotic Systems contains an extensive collection of examples and problems and: Puts the focus on the fundamentals of kinematics and dynamics as applied to robotic systems Presents the techniques of analytical mechanics of robotics Includes a review of advanced topics such as the recursive order N formulation Contains a wide array of design and analysis problems for robotic systems Written for students of robotics, Dynamics and Control of Robotic Systems offers a comprehensive review of the underlying principles and methods of the science of robotics. Flight Vehicle Dynamics and Control Rama K. Yedavalli, The Ohio State University, USA A comprehensive textbook which presents flight vehicle dynamics and control in a unified framework Flight Vehicle Dynamics and Control presents the dynamics and control of various flight vehicles, including aircraft, spacecraft, helicopter, missiles, etc, in a unified framework. It covers the fundamental topics in the dynamics and control of these flight vehicles, highlighting shared points as well as differences in dynamics and control issues, making use of the 'systems level' viewpoint. The book begins with the derivation of the equations of motion for a general rigid body and then delineates the differences between the dynamics of various flight vehicles in a fundamental way. It then focuses on the dynamic equations with application to these various flight vehicles, concentrating more on aircraft and spacecraft cases. Then the control systems analysis and design is carried out both from transfer function, classical control, as well as modern, state space control points of view. Illustrative examples of application to atmospheric and space vehicles are presented, emphasizing the 'systems level' viewpoint of control design. Key features: Provides a comprehensive treatment of dynamics and control of various flight vehicles in a single volume. Contains worked out examples (including MATLAB examples) and end of chapter homework problems. Suitable as a single textbook for a sequence of undergraduate courses on flight vehicle dynamics and control. Accompanied by a website that includes additional problems and a solutions manual. The book is essential reading for undergraduate students in mechanical and aerospace engineering, engineers working on flight vehicle control, and researchers from other engineering backgrounds working on related topics. Vehicle Dynamics and Control provides a comprehensive coverage of vehicle control systems and the dynamic models used in the development of these control systems. The control system applications covered in the book include cruise control, adaptive cruise control, ABS, automated lane keeping, automated highway systems, yaw stability control, engine control, passive, active and semi-active suspensions, tire-road friction coefficient estimation, rollover prevention, and hybrid electric vehicles. In developing the dynamic model for each application, an effort is made to both keep the model simple enough for control system design but at the same time rich enough to capture the essential features of the dynamics. A special effort has been made to explain the several different tire models commonly used in literature and to interpret them physically. 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Many of the papers represent significant advances in this area of research, and cover the development of control methods, including the control of dynamical systems subject to mixed constraints on both the control and state variables, and the development of a control design method for flexible manipulators with mismatched uncertainties. Advances in dynamic systems are presented, particularly in game-theoretic approaches and also the applications of dynamic systems methodology to social and environmental problems, for example, the concept of virtual biospheres in modeling climate change in terms of dynamical systems. A text/reference on analysis of structures that deform in use. Presents a new, integrated approach to analytical dynamics, structural dynamics and control theory and goes beyond classical dynamics of rigid bodies to incorporate analysis of flexibility of structures. Includes real-world examples of applications such as robotics, precision machinery and aircraft structures. Dynamics and Control of Nuclear Reactors presents the latest knowledge and research in reactor dynamics, control and instrumentation; important factors in ensuring the safe and economic operation of nuclear power plants. This book provides current and future engineers with a single resource containing all relevant information, including detailed treatments on the modeling, simulation, operational features and dynamic characteristics of pressurized light-water reactors, boiling light-water reactors, pressurized heavy-water reactors and molten-salt reactors. It also provides pertinent, but less detailed information on small modular reactors, sodium fast reactors, and gas-cooled reactors. Provides case studies and examples to demonstrate learning through problem solving, including an analysis of accidents at Three Mile Island, Chernobyl and Fukushima Daiichi Includes MATLAB codes to enable the reader to apply the knowledge gained to their own projects and research Features examples and problems that illustrate the principles of dynamic analysis as well as the mathematical tools necessary to understand and apply the analysis Publishers Note: Table 3.1 has been revised and will be included in future printings of the book with the following data: Group Decay Constant, λ (sec⁻¹) Delayed Neutron Fraction (bi) 1 0.0124 0.000221 2 0.0305 0.001467 3 0.111 0.001313 4 0.301 0.002647 5 1.14 0.000771 6 3.01 0.000281 Total delayed neutron fraction: 0.0067 The new 4th edition of Seborg's Process Dynamics Control provides full topical coverage for process control courses in the chemical engineering curriculum, emphasizing how process control and its related fields of process modeling and optimization are essential to the development of high-value products. A principal objective of this new edition is to describe modern techniques for control processes, with an emphasis on complex systems necessary to the development, design, and operation of modern processing plants. Control process instructors can cover the basic material while also having the flexibility to include advanced topics. The increased efficiency and quality constraints imposed on electrical energy systems have inspired a renewed research interest in the study of formal approaches to the analysis and control of power electronics converters. Switched systems represent a useful framework for modeling these converters and the peculiarities of their operating conditions and control goals justify the specific classification of "switched electronic systems". Indeed, idealized switched models of power converters introduce problems not commonly encountered when analyzing generic switched models or non-switched electrical networks. In that sense the analysis of switched electronic systems represents a source for new ideas and benchmarks for switched and hybrid systems generally. Dynamics and Control of Switched Electronic Systems draws on the expertise of an international group of expert contributors to give an overview of recent advances in the modeling, simulation and control of switched electronic systems. The reader is provided with a well-organized source of references and a mathematically-based report of the state of the art in analysis and design techniques for switched power converters. Intuitive language, realistic illustrative examples and numerical simulations help the reader to come to grips with the rigorous presentation of many promising directions of research such as: converter topologies and modulation techniques; continuous-time, discrete-time and hybrid models; modern control strategies for power converters; and challenges in numerical simulation. The guidance and information imparted in this text will be appreciated by engineers, and applied mathematicians working on system and circuit theory, control systems development, and electronic and energy conversion systems design. Satellites are used increasingly in telecommunications, scientific research, surveillance, and meteorology, and these satellites rely heavily on the effectiveness of complex onboard control systems. This 1997 book explains the basic theory of spacecraft dynamics and control and the practical aspects of controlling a satellite. The emphasis throughout is on analyzing and solving real-world engineering problems. For example, the author discusses orbital and rotational dynamics of spacecraft under a variety of environmental conditions, along with the realistic constraints imposed by available hardware. Among the topics covered are orbital dynamics, attitude dynamics, gravity gradient stabilization, single and dual spin stabilization, attitude maneuvers, attitude stabilization, and structural dynamics and liquid sloshing. Modelling, Dynamics and Control of Electrified Vehicles provides a systematic overview of EV-related key components, including batteries, electric motors, ultracapacitors and system-level approaches, such as energy management systems, multi-source energy optimization, transmission design and control, braking system control and vehicle dynamics control. In addition, the book covers selected advanced topics, including Smart Grid and connected vehicles. This book shows how EV work, how to design them, how to save energy with them, and how to maintain their safety. The book aims to be an all-in-one reference for readers who are interested in EVs, or those trying to understand its state-of-the-art technologies and future trends. Offers a comprehensive knowledge of the multidisciplinary research related to EVs and a system-level understanding of technologies Provides the state-of-the-art technologies and future trends Covers the fundamentals of EVs and their methodologies Written by successful researchers that show the deep understanding of EVs The continuing evolving capability of guided weapons demands ever more knowledge of their development. This modern and comprehensive book covers the control aspect of guidance of missiles, torpedoes, robots, and even animal predators, from the viewpoint of the pursuer. The text studies trajectories, zones of interception, the required manoeuvre effort, time of flight, launch envelopes, and stability of the guidance process. Mathematics at first-year university level is the only prerequisite. Acquaintance with feedback control theory would be helpful to the reader. Covers the control aspect of guidance of missiles, torpedoes, robots, and even animal

predators, from the viewpoint of the pursuer Studies trajectories, zones of interception, the required manoeuvre effort, time of flight, launch envelopes, and stability of the guidance process Vehicle Dynamics and Control: Advanced Methodologies features the latest information on advanced dynamics and vehicle motion control, including a comprehensive overview of passenger cars and articulated vehicles, fundamentals, and emerging developments. This book provides a unified, balanced treatment of advanced approaches to vehicle dynamics and control. It proceeds to cover advanced vehicle control strategies, such as identification and estimation, adaptive nonlinear control, new robust control techniques, and soft computing. Other topics, such as the integrated control of passenger cars and articulated heavy vehicles, are also discussed with a significant amount of material on engineering methodology, simulation, modeling, and mathematical verification of the systems. This book discusses and solves new challenges in vehicle dynamics and control problems and helps graduate students in the field of automotive engineering as well as researchers and engineers seeking theoretical/practical design procedures in automotive control systems. Provides a vast spectrum of advanced vehicle dynamics and control systems topics and current research trends Provides an extensive discussion in some advanced topics on commercial vehicles, such as dynamics and control of semitrailer carrying liquid, integrated control system design, path planning and tracking control in the autonomous articulated vehicle

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